Tip characterizer

AFM

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A P P L I C A T I O N

The AFM-tip characterizer contains patterns for an in-situ determination of the AFM-tip shape.

DESCRIPTION

The structures for the AFM-tip characterizer offer a series of very smooth and sharp etched line-space structures in silicon with vertical side-walls. Each calibration chip has a size of 8 x 8 mm². In the centre of the calibration chip, where the two-stage finding structure ends, 3 groups of 5 linespace structures with different nominal widths (300, 500 and 800 nm) are arranged. The space between the lines is about 1 μ m. Each group is nominally 20 μ m long. The structures are sharp-edged with edge radii of less than 2 nm. The edge roughness is well below 5 nm (3 σ).





SEM-Micrograph of the calibration pattern (groups with different CD-widths from 300 nm to 800 nm).

SPECIFICATIONS

Substrate	• Material: <110 > Si
	Chip dimension: 8x8 mm ²
	 Surface roughness: <1nm
Finding structures	 Grooves in the Si-substrate
	• Depth (in general): 1µm
Types of grating	• 1-dim
Size of grating	• Normally 10 x 10 µm²
Linewidths (CD)	• Nominal: 300 nm, 500 nm, 800 nm
	• Linewidth variation along the lines
	(within a central part of $10 \mu m$):
	< 5nm 1σ

Pitches	• 1µm + CD value
	- Uncertainty of mean pitch: 3 nm 1 σ
Structure depth	• in general: 1µm
Edge radius	• < 2nm
Edge roughness	• ± 4 nm (3σ)
Sidewall angle	• 89°
Traceability	 CD, pitch and depth-calibration
	made by the PTB Braunschweig
	on request.

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STRUCTURE DETAILS



SEM-picture of the 300 nm calibration group with very small edge roughness (tilt view 60°)



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Details of the very smooth, highly parallel and sharp etched silicon structures (SEM-micrograph of the 800 nm group, tilt 0°)

PRINCIPLE OF DETECTION OF THE AFM-TIP SHAPE AND TIP RADIUS



AFM-pictures: Courtesy of Th. Sulzbach, Nanoworld GmbH

The method of the in-situ characterization is based on the AFM-measurement of a well-known line-space structure and the calculation of the tip shape from the measurement result (see figure). The sidewalls of the calibration structures are steeper than the half-cone angle of the tip. Therefore, the measured sidewalls reflect the shape of the tip. If, in addition to that, the edge radius of the calibration structures can be neglected, compared to the tip radius, then the measured radii also represent the tip radius. By means of these standards the shape and the radius of the tip can be quickly quantified before and after the AFM measuring process.



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